

Chapter 6

Queues

Topics

- FIFO (first0in-first0out) structure
- Implementations: formula-based and linked classes
- Applications:
 - railroad-switching problem
 - **shortest path for a wire that is to connect two points**
 - **pixels labeling**
 - machine shop simulation

Queues

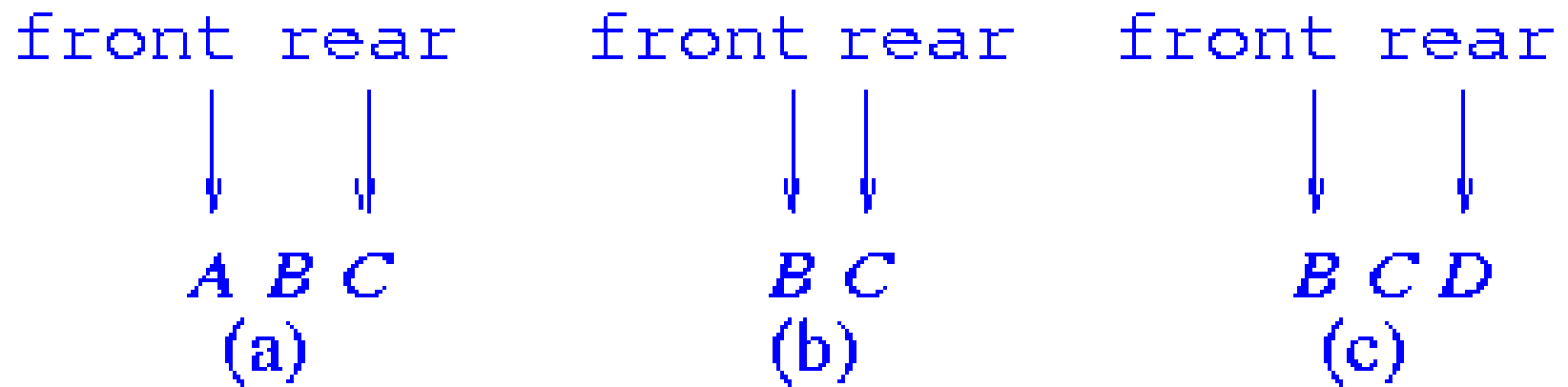


Figure 6.1 Sample queues

Abstract data type

AbstractDataType *Queue* {

instances

ordered list of elements; one end is called the *front*; the other is the *rear*;

operations:

Create (): Create an empty queue;

IsEmpty (): Return *true* if queue is empty, return *false* otherwise;

IsFull (): Return *true* if queue is full, return *false* otherwise;

First (): Return first element of queue;

Last (): Return last element of queue;

Add (x): Add element *x* to the queue;

Delete (x): Delete front element from queue and put it in *x*;

}

ADT 6.1 The abstract data type queue

Queues 1

- $location(i) = i - 1$
- add - $O(1)$
- delete - $\Theta(n)$ (need to slide items to front)

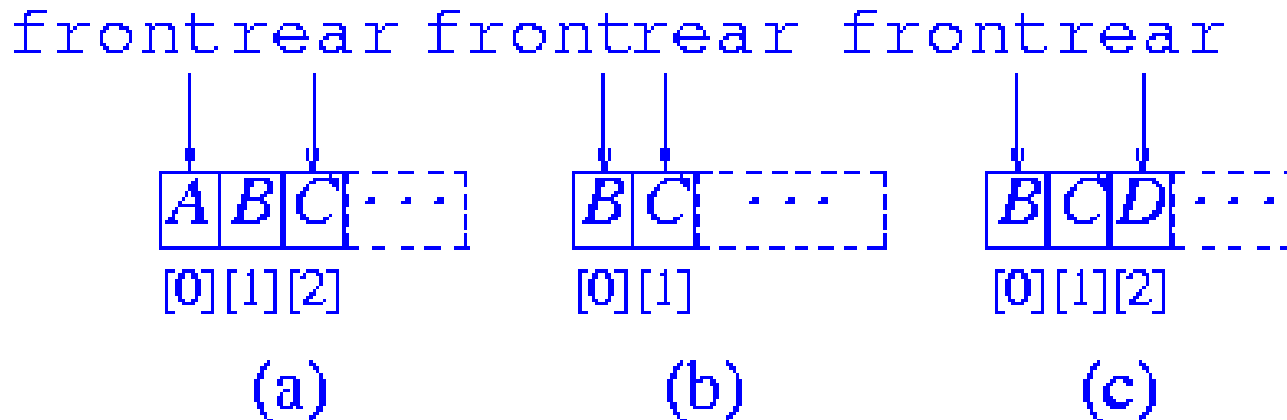


Figure 6.2 Queues of Figure 6.1 using formula (6.1)

Queues 2

- $location(i) = location(1) + i - 1$
- add - worst-case $\Theta(n)$ (when buffer is full)
- delete - $O(1)$

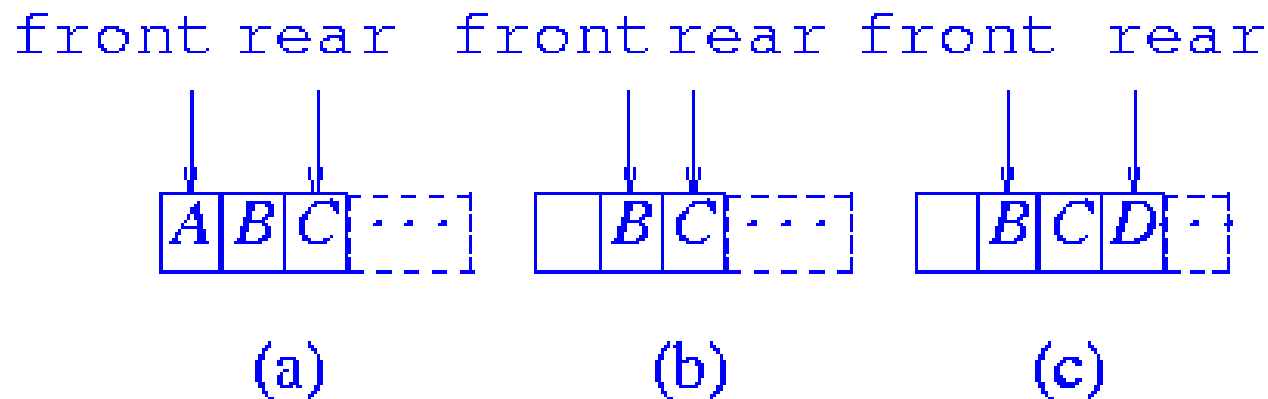


Figure 6.3 Queues of figure 6.1 using formula 6.2

Shifting

when $rear = MaxSize - 1$ and $front > 0$

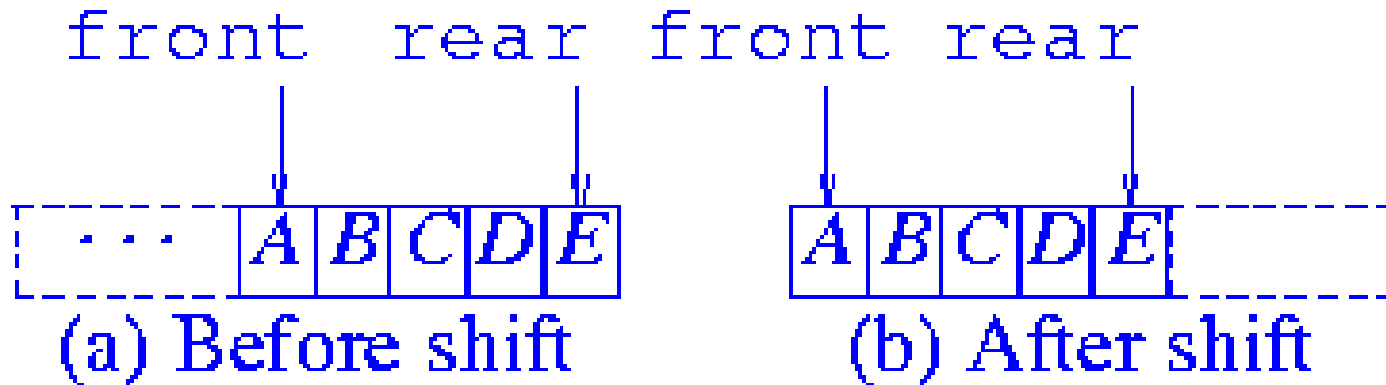


Figure 6.4 Shifting a queue

Queues 3

- $location(i) = (location(1) + i - 1) \% MaxSize$
- add - $\Theta(1)$
- delete - $\Theta(1)$

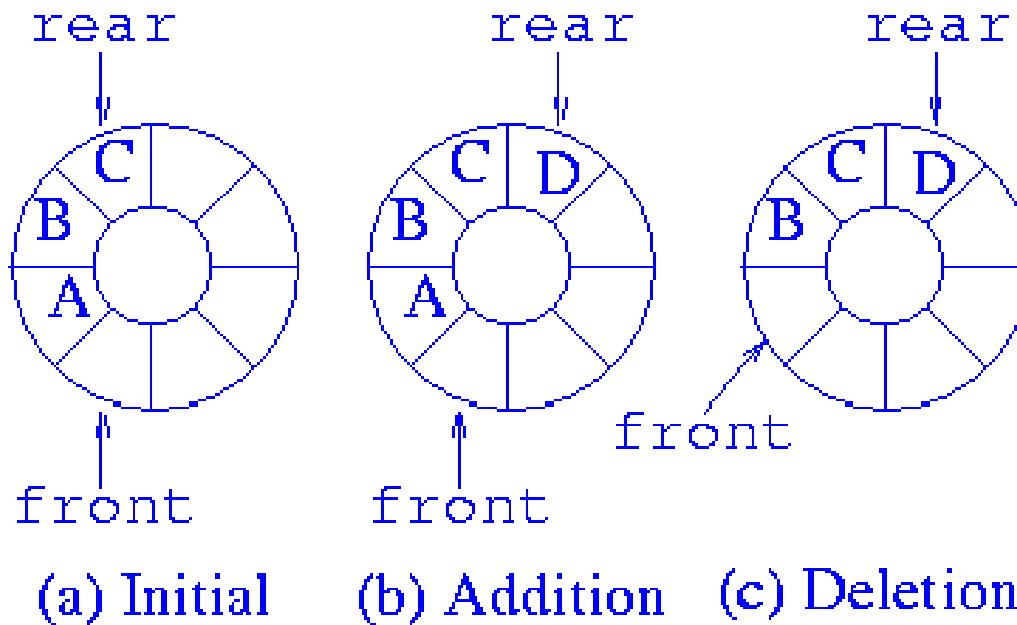


Figure 6.5 Circular queues

Empty and full queue

- Empty queue:
 $front = rear$
- full queue: can only hold up to $MaxSize - 1$ elements

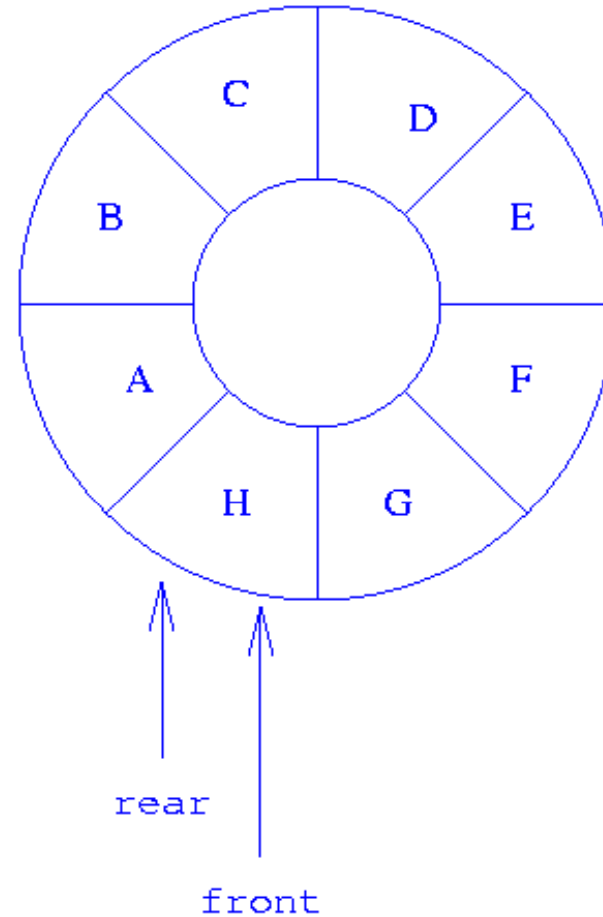


Figure 6.6 A circular queue with $MaxSize$ elements

Formula-based class Queue

```
template <class T>
class Queue {
// FIFO objects
public :
    Queue(int MaxQueueSize = 10);
    ~LinkedQueue() {delete [] queue;}
    bool IsEmpty() const {return front == rear;}
    bool IsFull() const
        {return(((rear+1) % MaxSize == front)?1:0);}
    T First() const ; // return front element
    T Last() const ; // return last element
    Queue<T>& Add(const T& x);
    Queue<T>& Delete(T& x);
private :
    int front; // one counterclockwise from first
    int rear; // last element
    int MaxSize; // size of array queue
    T *queue; // element array
};
```

Program 6.1 Formula-based class Queue

Constructor -

$\Theta(1)$ when T is internal; $O(\text{MaxStackSize})$ when T is user-defined

First - $\Theta(1)$

```
template <class T>
Queue<T>::Queue(int MaxQueueSize)
{
    // Create an empty queue whose capacity
    // is MaxQueueSize.
    MaxSize = MaxQueueSize + 1;
    queue = new T[MaxSize];
    front = rear = 0;
}

template <class T>
T Queue<T>::First() const
{
    // Return first element of queue. Throw
    // OutOfBounds exception if the queue is empty.
    if (IsEmpty()) throw OutOfBounds();
    return queue[(front + 1) % MaxSize];
}
```

Last - $\Theta(1)$

```
template <class T>
T Queue<T>::Last() const
{
    // Return last element of queue.  Throw
    // OutOfBounds exception if the queue is empty.
    if (IsEmpty()) throw OutOfBounds();
    return queue[rear];
}
```

Program 6.2 Queue functions using
formula-based representation (continues)

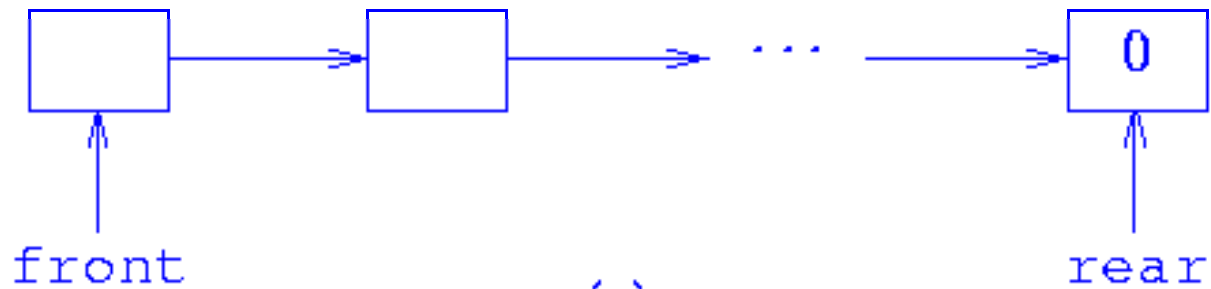
Add and Delete - $\Theta(1)$

```
template <class T>
Queue<T>& Queue<T>::Add(const T& x)
{ // Add x to the rear of the queue. Throw
  // NoMem exception blue if the queue is full.
  if (IsFull()) throw NoMem();
  rear = (rear + 1) % MaxSize;
  queue[rear] = x;
  return *this ;
}

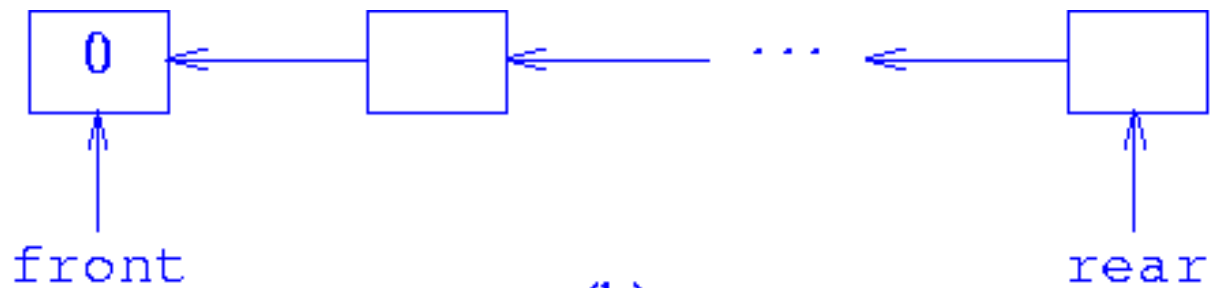
template <class T>
Queue<T>& Queue<T>::Delete(T& x)
{ // Delete first element and put it in x. Throw
  // OutOfBounds exception if the queue is empty.
  if (IsEmpty()) throw OutOfBounds();
  front = (front + 1) % MaxSize;
  x = queue[front];
  return *this ;
}
```

Program 6.3 Queue functions using
formula-based representation (concluded)

Linked presentation



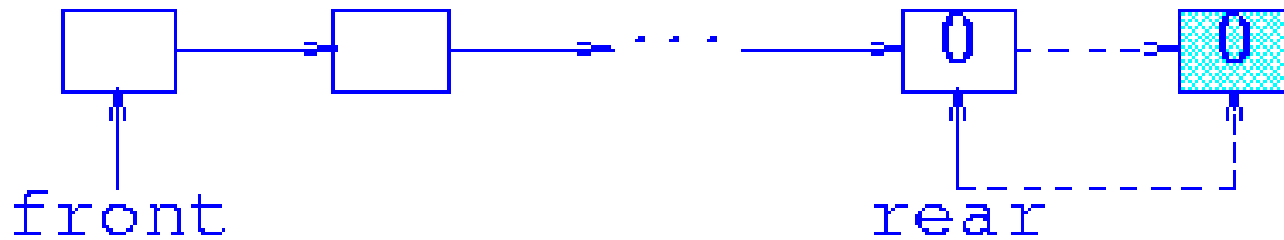
(a)



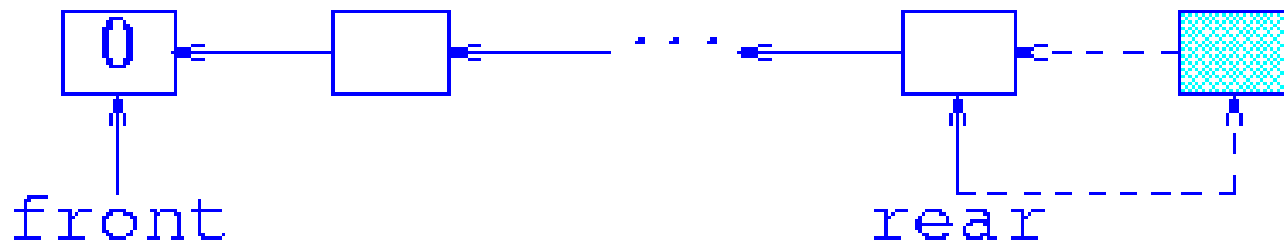
(b)

Figure 6.7 Linked queues

Addition



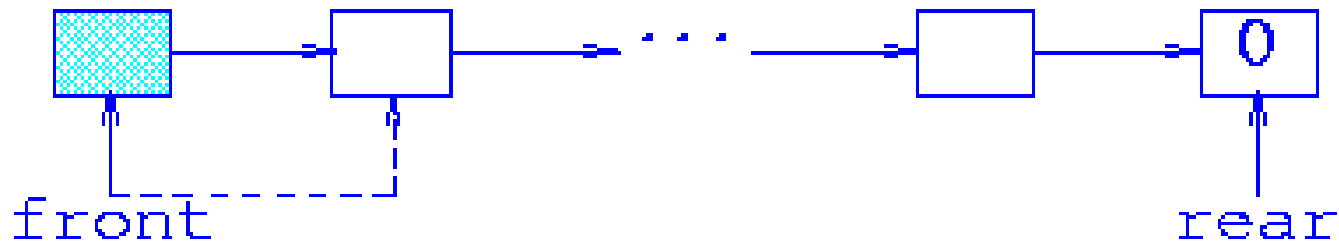
(a) Addition to figure 6.7 (a)



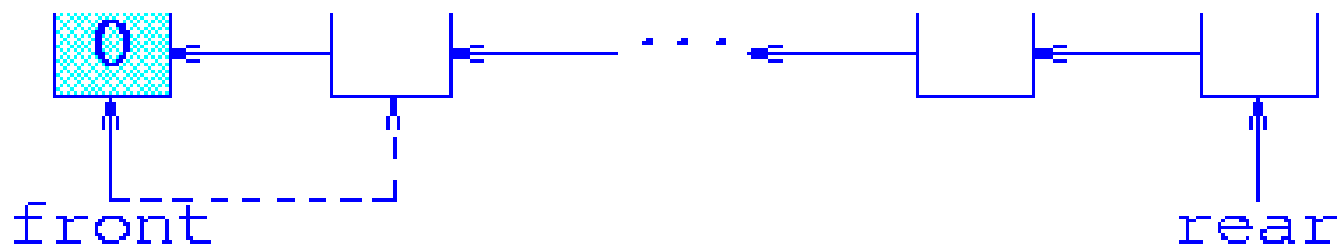
(b) Addition to figure 6.7(b)

Figure 6.8 Addition to a linked queue

Deletion



(a) Deletion from figure 6.7(a)



(b) Deletion from figure 6.7 (b)

Figure 6.9 Deletion from a linked queue

Class definition

```
template <class T>
class LinkedQueue {
// FIFO objects
public :
    //constructor
    LinkedQueue() {front = rear = 0;}
    ~LinkedQueue(); // destructor
    bool IsEmpty() const
        {return ((front) ? false : true);}
    bool IsFull() const ;
    T First() const ; // return first element
    T Last() const ; // return last element
    LinkedQueue<T>& Add(const T& x);
    LinkedQueue<T>& Delete(T& x);
private :
    Node<T> *front; // pointer to first node
    Node<T> *rear; // pointer to last node
};
```

Program 6.4 Class definition for a linked queue

Destructor - $\Theta(n)$

```
template <class T>
LinkedList<T>::~~LinkedList()
{ // Queue destructor. Delete all nodes.
    Node<T> *next;
    while (front) {
        next = front->link;
        delete front;
        front = next;
    }
}
```

IsFull - $\Theta(1)$

```
template <class T>
bool LinkedListQueue<T>::IsFull() const
{ // Is the queue full?
    Node<T> *p;
    try {p = new Node<T>;
        delete p;
        return false;}
    catch (NoMem) {return true;}
}
```

First and Last - $\Theta(1)$

```
template <class T>
T LinkedList<T>::First() const
{
    // Return first element of queue. Throw
    // OutOfBounds exception if the queue is empty.
    if (IsEmpty()) throw OutOfBounds();
    return front->data;
}
```

```
template <class T>
T LinkedList<T>::Last() const
{
    // Return last element of queue. Throw
    // OutOfBounds exception if the queue is empty.
    if (IsEmpty()) throw OutOfBounds();
    return rear->data;
}
```

Program 6.5 Linked queue function implementations (continues)

Add - $\Theta(1)$

```
template <class T>
LinkedList<T>& LinkedList<T>::Add(const T& x)
{ // Add x to rear of queue. Do not catch
  // possible NoMem exception thrown by new .

  // create node for new element
  Node<T> *p = new Node<T>;
  p->data = x;
  p->link = 0;

  // add new node to rear of queue
  if (front) rear->link = p; // queue not empty
  else front = p; // queue empty
  rear = p;

  return *this ;
}
```

Delete - $\Theta(1)$

```
template <class T>
LinkedQueue<T>& LinkedQueue<T>::Delete(T& x)
{ // Delete first element and put it in x. Throw
  // OutOfBounds exception if the queue is empty.

    if (IsEmpty()) throw OutOfBounds();

    // save element in first node
    x = front->data;

    // delete first node
    Node<T> *p = front;
    front = front->link;
    delete p;

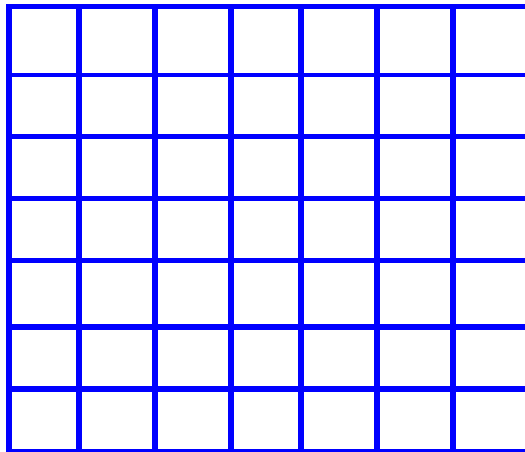
    return *this ;
}
```

Program 6.6 Linked queue function implementations (concluded)

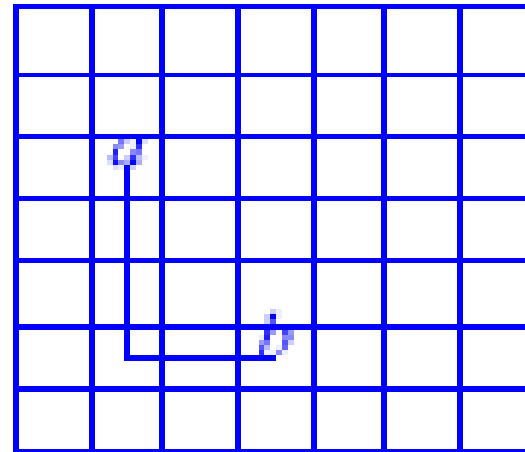
Wire-Routing Problem

- Need to route wires from A to B using the **shortest-path**.
- Routing region can be represented with a grid: an $n \times m$ matrix of squares
- wire runs midpoint of one square to midpoint of another making only right-angles.
- Grid squares that already have wires in them are blocked.

Wire-Routing Problem



(a) A 7×7 grid



(b) A wire between a and b

Figure 6.11 Wire-routing example

Wire-Routing Problem

- Begin at source a
- label its reachable neighbors with 1
- next the reachable neighbors of distance 1 squares are labeled 2.
- Continue labeling processing until either reach destination b or have no more reachable neighbors.
- If b is reached, label it with its distance.

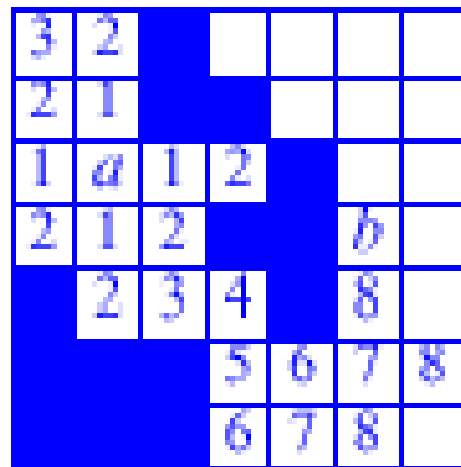
Wire-Routing Problem

To construct shortest path,

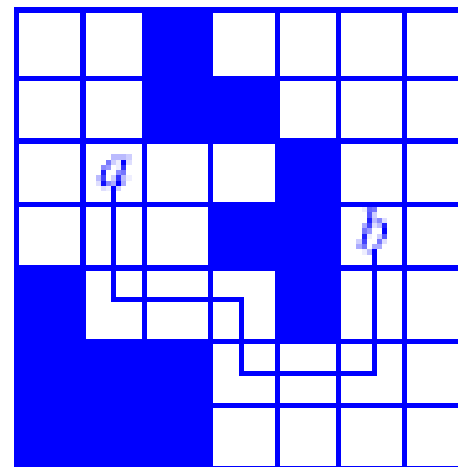
- Start from b and move to anyone of its neighbors labeled 1 less than b 's label.
- From the neighbor found in previous step, move to one of its neighbors whose label is 1 less
- repeat until square a is reached

The sequence of neighbors collected forms the shortest path.

Wire-Routing Problem



(a) Distance labeling



(b) Wire path

Figure 6.12 Wire routing

```

bool FindPath(Position start, Position finish,
              int & PathLen, Position * &path)
{
    // Find a path from start to finish.
    // Return true if successful, false if impossible
    // Throw NoMem exception if inadequate space.

    if ((start.row == finish.row) &&
        (start.col == finish.col))
        {PathLen = 0; return true;} // start=finish

    // initialize wall of blocks around grid
    for (int i = 0; i <= m+1; i++) {
        // bottom & top
        grid[0][i] = grid[m+1][i] = 1;
        // left & right
        grid[i][0] = grid[i][m+1] = 1;    }
}

```

```
// initialize offsets
Position offset[4];
offset[0].row = 0; offset[0].col = 1; // right
offset[1].row = 1; offset[1].col = 0; //down
offset[2].row = 0; offset[2].col = -1; //left
offset[3].row = -1; offset[3].col = 0; //up

int NumOfNbrs = 4; //neighbors of a grid position
Position here, nbr;
here.row = start.row;
here.col = start.col;
grid[start.row][start.col] = 2; // block
```

Program 6.9 Find a wire route

Railroad Car Rearrangement

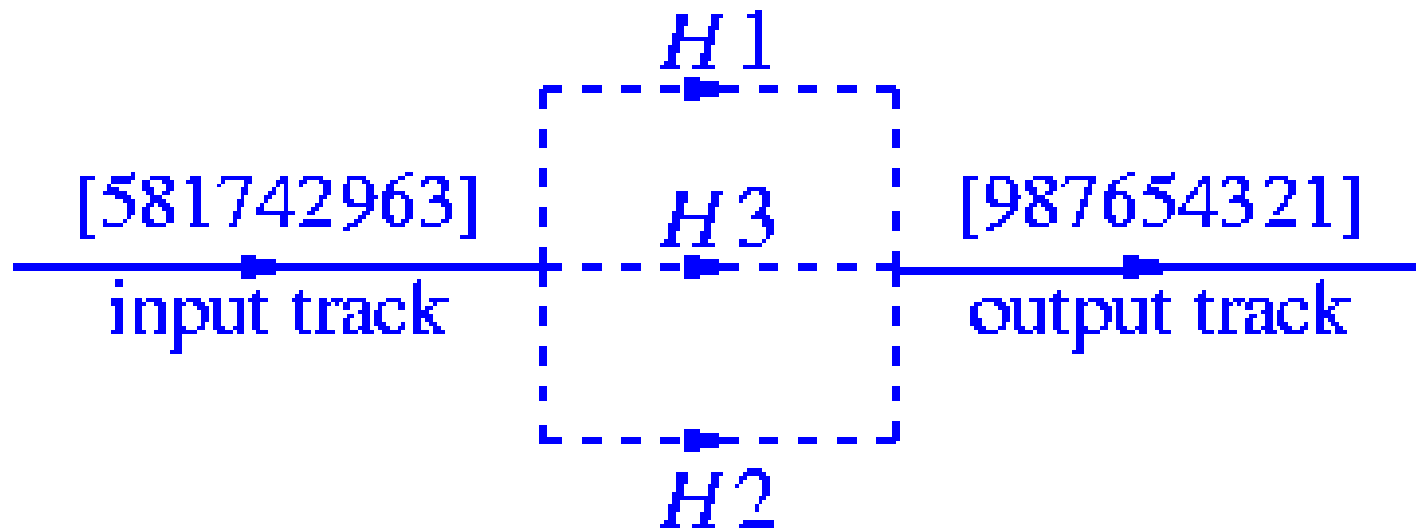


Figure 6.10 A three-track example

Rules

- Reserve Hk for moving cars directly from the input track to the output track
- Move car c to a holding track that contains only cars with a smaller label; if there are several such tracks, select one with largest label at its left end; otherwise, select an empty track (if one remains)

Output

```
void Output(int & minH, int & minQ,
            LinkedQueue<int > H[], int k, int n)
{ // Move from hold to output and update minH
    and minQ.

    int c; // car index
    //delete smallest car minH from queue minQ
    H[minQ].Delete(c);
    cout << "Move car" << minH
         << "from holding track"
         << minQ << " to output" << endl;
    // find new minH and minQ
    // by checking front of all queues
    minH = n + 2;
    for (int i = 1; i <= k; i++)
        if (!H[i].IsEmpty() &&
            (c = H[i].First()) < minH) {
            minH = c;
            minQ = i;}
}
```

Program 6.7 Rearranging cars using queues
(continues)

Hold

```
bool Hold(int c, int & minH, int &minQ,  
LinkedQueue<int > H[], int k)  
{// Add car c to a holding track.  
// Return false if no feasible holding track.  
// Throw NoMem exception if no queue space.  
// Return true otherwise.  
  
    // find best holding track for car c  
    // initialize  
    int BestTrack = 0, // best track so far  
        BestLast = 0, // last car in BestTrack  
        x; // a car index
```

Hold (continue)

```
// scan holding tracks
for (int i = 1; i <= k; i++)
    if (!H[i].IsEmpty()) { // track i not empty
        x = H[i].Last();
        if (c > x && x > BestLast) {
            // track i has bigger car at end
            BestLast = x;
            BestTrack = i;}
    }
else // track i empty
    if (!BestTrack) BestTrack = i;

if (!BestTrack) // no track available
return false;
```

Hold (continue)

```
// add c to best track
H[BestTrack].Add(c);
cout << "Move car " << c << " from input "
      << "to holding track " << BestTrack
      << endl;

// update minH and minQ if needed
if (c < minH) {minH = c;
              minQ = BestTrack;}

return true;
}
```

Program 6.7 Rearranging cars using queues
(concluded)

Output without using queue

```
void Output(int NowOut, int Track, int & Last)
{
    // Move car NowOut from hold to output,
    //update Last.
    cout << "Move car " << NowOut
         << " from holding track "
         << Track << " to output" << endl;
    if (NowOut == Last) Last = 0;
}

bool Hold(int c, int last[],
          int track[],int k)
{
    // Add car c to a holding track.
    // Return false if no feasible holding track.
    // Return true otherwise.
    // find best holding track for car c
    // initialize
    int BestTrack = 0, // best track so far
        BestLast = 0; // last car in BestTrack
```

Output without using queue (continue)

```
// scan holding tracks
for (int i = 1; i <= k; i++) // find best track
    if (last[i]) { // track i not empty
        if (c > last[i] && last[i] > BestLast){
            // track i has bigger car at end
            BestLast = last[i];
            BestTrack = i;}
    }
else // track i empty
    if (!BestTrack) BestTrack = i;
```

Output without using queue (continue)

```
if (!BestTrack) // no track available
    return false;
// add c to best track
track[c] = BestTrack;
last[BestTrack] = c;
cout << "Move car " << c << " from input "
      << "to holding track " << BestTrack
      << endl;

return true;
}
```

Program 6.8 Rearranging cars without the use
of a queue (continues)

Railroad without using queue - $O(n \log k)$

```
bool Railroad(int p[], int n, int k)
{
    // k track rearrangement of car order p[1:n].
    // Return true if successful, false if impossible.
    // Throw NoMem exception if inadequate space.

    // initialize arrays last and track
    int *last = new int [k + 1];
    int *track = new int [n + 1];
}
```

Railroad without using queue (continue)

```
for (int i = 1; i <= k; i++)
    last[i] = 0; // track i is empty
for (int i = 1; i <= n; i++)
    track[i] = 0; // car i is on no track
k--; // keep track k open for direct moves

// initialize index of next car
// that goes to output
int NowOut = 1;
// output cars in order
for (int i = 1; i <= n; i++)
    if (p[i] == NowOut) { // send straight to output
        cout << "Move car " << p[i]
            << "from input to output" << endl;
        NowOut++;
    }
```


Railroad without using queue (continue)

```
    // output from holding tracks
    while (NowOut <= n && track[NowOut]) {
        Output(NowOut, track[NowOut], last[NowOut]);
        NowOut++;
    }
}
else { // put car p[i] in a holding track
    if (!Hold(p[i], last, track, k))
        return false;}

return true;
}
```

Program 6.8 Rearranging cars without the use of a queue (concluded)

Image-Component labeling

		1				
		1	1			
				1		
			1	1		
	1			1		1
1	1	1				1
1	1	1			1	1

(a) A 7×7 image

		2				
		2	2			
				3		
			3	3		
	4			3		5
4	4	4				5
4	4	4			5	5

(b) Labeled components

Figure 6.13 Image-component labeling

Offset

move	direction	offset [move] .row	offset [move] .col
0	right	0	1
1	down	1	0
2	left	0	-1
3	up	-1	0

Figure 5.18 Table of offsets

Wall of blank pixels (0)

Note: change 1 to 0

```
1 1 1 1 1 1 1 1 1 1 1
1 0 1 1 1 1 1 0 0 0 1
1 0 0 0 0 0 1 0 1 0 1
1 0 0 0 1 0 1 0 0 0 1
1 0 1 0 1 0 1 0 1 1 0 1
1 0 1 0 1 0 1 0 1 0 0 1
1 0 1 1 1 0 1 0 1 0 1 1
1 0 1 0 0 0 1 0 1 0 1 1
1 0 1 0 1 1 1 0 1 0 0 1
1 1 0 0 0 0 0 0 1 0 0 1
1 0 0 0 0 1 1 1 1 0 0 1
1 1 1 1 1 1 1 1 1 1 1
```

Figure 5.15 Maze of figure 5.8 with wall of ones around it

Component labeling

```
void Label()
{
    // Label image components.
    // initialize wall of 0 pixels
    for (int i = 0; i <= m+1; i++) {
        // bottom & top
        pixel[0][i] = pixel[m+1][i] = 0;
        // left & right
        pixel[i][0] = pixel[i][m+1] = 0;
    }
    // initialize offsets
    Position offset[4];
    offset[0].row = 0; offset[0].col = 1; // right
    offset[1].row = 1; offset[1].col = 0; // down
    offset[2].row = 0; offset[2].col = -1; // left
    offset[3].row = -1; offset[3].col = 0; // up

    int NumOfNbrs = 4; // neighbors of a pixel position
    LinkedQueue<Position> Q;
    int id = 1; // component id
    Position here, nbr;
```

Component labeling (continue)

```
//scan all pixels labeling components
for (int r = 1; r <= m; r++) // row r of image
  for (int c = 1; c <= m; c++) // column c
    if (pixel[r][c] == 1) { // new component
      pixel[r][c] = ++id; // get next id
      here.row = r; here.col = c;
      do { // find rest of component
        for (int i = 0; i < NumOfNbrs; i++) {
          // check all neighbors of here
          nbr.row = here.row + offset[i].row;
          nbr.col = here.col + offset[i].col;
          if (pixel[nbr.row][nbr.col] == 1) {
            pixel[nbr.row][nbr.col] = id;
            Q.Add(nbr);} // end of if and for
          //any unexplored pixels in component?
          if (Q.IsEmpty()) break ;
          Q.Delete(here); //a component pixel
        } while (true);
      } // end if, for c, for r, and Label
```

Program 6.10 Component labelling being the use of a queue

Evaluation

- Initialize the wall - $\Theta(m)$
- Initialize offsets - $\Theta(1)$
- identifying and labeling pixels of one component - $\Theta(\# \text{ of pixels in component})$
- identifying and labeling nonseed component - $\Theta(\# \text{ of pixels in component pixels in image}) = O(m^2)$
- Overall complexity - $O(m^2)$

End of Chapter 6